

**WHY THERE IS NO STATISTICAL  
TEST FOR CONFOUNDING,  
WHY MANY THINK THERE IS,  
AND WHY THEY ARE ALMOST RIGHT**

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## Definition 6.2.1

### (No-Confounding; Causal Definition)

Let  $M$  be a causal model of the data-generating process—that is, a formal description of how the value of each observed variable is determined. Denote by  $P(y|do(x))$  the probability of the response event  $Y = y$  under the hypothetical intervention  $X = x$ , calculated according to  $M$ . We say that  $X$  and  $Y$  are not confounded in  $M$  if and only if

$$P(y|do(x)) = P(y|x) \quad (6.10)$$

for all  $x$  and  $y$  in their respective domains, where  $P(y|x)$  is the conditional probability generated by  $M$ .

## Definition 6.2.2

### (No-Confounding: Associational Criterion)

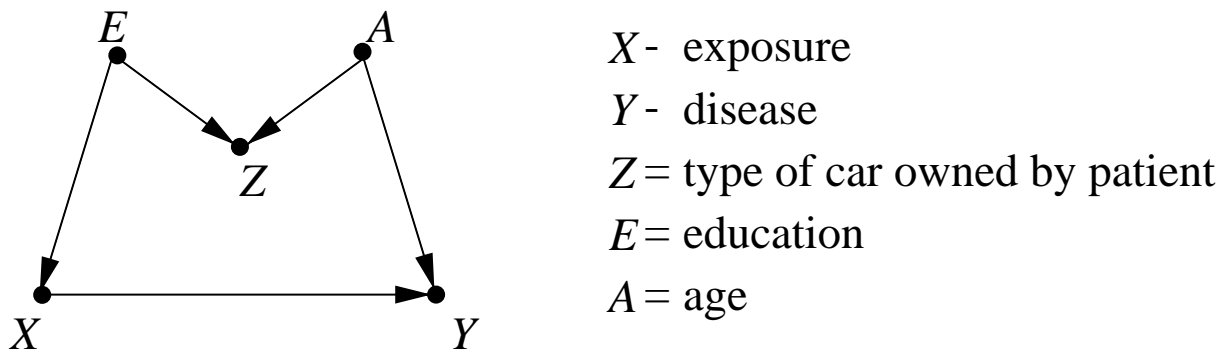
Let  $T$  be the set of variables in a problem that are not affected by  $X$ . We say that  $X$  and  $Y$  are not confounded in the presence of  $T$  if every member  $Z$  of  $T$  satisfies at least one of the following):

( $U_1$ )  $Z$  is not associated with  $X$ ,  
(i.e.,  $P(x|z) = P(x)$ );

( $U_2$ )  $Z$  is not associated with  $Y$  conditional  
on  $X$  (i.e.,  $P(y|z, x) = P(y|x)$ ).

### Example 6.3.1

Imagine a situation where **exposure** ( $X$ ) is influenced by a person's **education** ( $E$ ), **disease** ( $Y$ ) is influenced by both exposure and **age** ( $A$ ), and **car type** ( $Z$ ) is influenced by both **age** ( $A$ ) and **education** ( $E$ ). These relationships are shown schematically in Figure 6.3



**Figure 6.3**

Both ( $U_1$ ) and ( $U_2$ ) fail on  $Z$ , yet  $X$  and  $Y$  are not confounded.

Moreover, adjusting for  $Z$  would yield a **biased** result

$$P(y|do(x)) \neq \sum_z P(y|x, z)P(z)$$

## MODIFIED ASSOCIATIONAL CRITERION

### Definition 6.3.2

#### (No-Confounding; Modified Associational Criterion)

Let  $T$  be the set of variables in a problem that are not affected by  $X$  but **may potentially affect  $Y$** . We say that  $X$  and  $Y$  are unconfounded by the presence of  $T$  if and only if every member  $Z$  of  $T$  satisfies either  $(U_1)$  or  $(U_2)$  of Definition 6.2.2.

$(U_1)$   $Z$  is not associated with  $X$ ,  
(i.e.,  $P(x|z) = P(x)$ ),

$(U_2)$   $Z$  is not associated with  $Y$  within  
strata of  $X$  (i.e.,  $P(y|z, x) = P(y|x)$ ).

### Example 6.3.3

Consider a causal model defined by the linear equations:

$$x = \alpha z + \epsilon_1 \quad (6.11)$$

$$y = \beta x + \gamma z + \epsilon_2 \quad (6.12)$$

where  $\epsilon_1$  and  $\epsilon_2$  are correlated unmeasured variables having  $cov(\epsilon_1, \epsilon_2) = r$  and where  $Z$  is an exogenous variable that is uncorrelated with  $\epsilon_1$  or  $\epsilon_2$ .

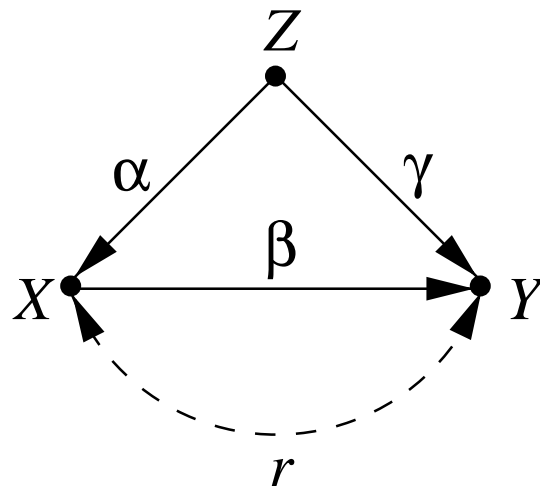


Figure 6.4

If  $r = -\alpha\gamma$  then  $r_{YX} = \beta$ .

Thus,  $(X, Y)$  is not confounded, though  $(U_1)$  and  $(U_2)$  are violated.

## STABLE UNBIASEDNESS

### Definition 6.4.1

#### (Stable Unbiasedness)

Let  $A$  be a set of assumptions (or restrictions) on the data-generating process, and let  $C_A$  be a class of causal models satisfying  $A$ . The effect estimate of  $X$  on  $Y$  is said to be **stably unbiased** given  $A$  if  $P_M(y|do(x)) = P(y|x)$  holds in every model  $M$  in  $C_A$ . Correspondingly, we say that the pair  $(X, Y)$  is **stably unconfounded**, given  $A$ .

## EXAMPLE OF MODEL ASSUMPTIONS: GRAPHS

### Definition 6.4.2

#### **Structurally Stable No-Confounding)**

Let  $A_D$  be the set of assumptions embedded in a causal diagram  $D$ . We say that  $X$  and  $Y$  are **stably unconfounded** given  $A_D$  if  $P(y|do(x)) = P(y|x)$  holds in every parameterization of  $D$ .

By “parameterization” we mean an assignment of functions to the links of the diagram and prior probabilities to the background variables in the diagram.



### **Theorem 6.4.3 (Common-Cause Principle)**

Let  $A_D$  be the set of assumptions embedded in an acyclic causal diagram  $D$ . Variables  $X$  and  $Y$  are stably unconfounded given  $A_D$  if and only if  $X$  and  $Y$  have no common ancestor in  $D$ .

(More precisely, All back-door paths from  $X$  to  $Y$  are blocked.)

### **Theorem 6.4.4 (Criterion for Stable No-Confounding)**

Let  $A_Z$  denote the assumptions that (i) the data are generated by some (unspecified) acyclic model  $M$  and (ii)  $Z$  is a variable in  $M$  that is unaffected by  $X$  but may possibly affect  $Y$ . If both of the associational criteria  $(U_1)$  and  $(U_2)$  of Definition 6.2.2 are violated, then  $(X, Y)$  are not stably unconfounded given  $A_Z$ .

By “possibly affecting  $Y$ ” we mean:  $A_Z$  does not contain the assumption that  $Z$  does not affect  $Y$ . In other words, the diagram associated with  $M$  must contain a directed path from  $Z$  to  $Y$ .

Finding just *any* variable  $Z$  that satisfies  $A_Z$  and violates  $(U_1)$  and  $(U_2)$  permits us to disqualify  $(X, Y)$  as stably unconfounded (though  $(X, Y)$  may be incidentally unconfounded in the particular experimental conditions prevailing in the study).

# COLLAPSIBILITY VS. NONCONFOUNDING

## Definition 6.5.1

### (Collapsibility)

Let  $g[P(y, x)]$  be any functional that measures the association between  $Y$  and  $X$  in the joint distribution  $P(x, y)$ . We say that  $g$  is **collapsible** on a variable  $Z$  if

$$E_z g[P(x, y|z)] = g[P(x, y)]$$

## Corollary 6.5.2

### (Stable No-Confounding Implies Collapsibility)

Let  $Z$  be any variable that is not affected by  $X$  and that may possibly affect  $Y$ . Let  $g[P(x, y)]$  be any linear functional that measures the association between  $X$  and  $Y$ . If  $g$  is not collapsible on  $Z$ , then  $X$  and  $Y$  are not stably unconfounded.